## Practical guide to loop integration

Summer Term 2024 Dr Y. Ulrich

Exercise Sheet 6

Issued: 21 May 2024

https://yannickulrich.com/loop-integration

**Exercise 1:** Multidimensional Frobenius method In this problem we will explore the Frobenius method. Consider the following system of differential equations

$$\frac{\partial \vec{f}}{\partial x} = \underbrace{\begin{pmatrix} \frac{2-x}{1-x} & -\frac{1}{1-x} \\ -x & \frac{x}{1-x} \end{pmatrix}}_{M} \vec{f}.$$
(1)

A solution of this is given by

$$\vec{f} = \left(\frac{\log(1-x)}{1-x}, \frac{1}{1-x} + \log(1-x)\right)^T.$$
 (2)

You may use this solution step-by-step to verify your working though in a real-life example, you would obviously not know it.

- a) Construct the matrices  $M^{(j)}$  for j = 0, j = 1, and j = 2. Write down the matrices  $\overline{M}$  and  $\widetilde{M}$
- b) Find a vector  $\vec{c}$  from the left-nullspace of  $\tilde{M}$  such that  $\vec{c}\tilde{M} = 0$ .
- c) Make an ansatz for  $f_1 = x^r \sum x^i a_i$  and calculate  $\vec{c} \cdot (f_1, \partial_x f_1, \partial_x^2 f_1)$ . Find the biggest  $r, a_1, a_2,$  and  $a_3$ .
- d) Construct  $\vec{f}$  by inverting  $\tilde{M}$ .

**SOLUTION:** We begin by verifying that (2) is indeed a valid solution of (1).

a) Using the recursive definition

$$M^{(0)} = 1$$
 and  $M^{(j)} = \frac{\partial M^{(j-1)}}{\partial x} - M^{(j-1)}M$ , (3)

we have

$$M^{(0)} = \begin{pmatrix} 1 & 0\\ 0 & 1 \end{pmatrix} \tag{4}$$

$$M^{(1)} = M \tag{5}$$

$$M^{(2)} = \begin{pmatrix} \frac{5-3x}{(1-x)^2} & -\frac{3}{(1-x)^2} \\ \frac{1+x}{1-x} & \frac{1+x}{(1-x)^2} \end{pmatrix}.$$
 (6)

With this we can just read of

$$\bar{M} = \begin{pmatrix} 1 & 0\\ \frac{2-x}{1-x} & \frac{1}{x-1} \end{pmatrix} \tag{7}$$

$$\tilde{M} = \begin{pmatrix} 1 & 0\\ \frac{2-x}{1-x} & \frac{1}{x-1}\\ \frac{5-3x}{(1-x)^2} & -\frac{3}{(1-x)^2} \end{pmatrix}.$$
(8)

At this point we may verify that

$$\frac{\partial^{j} \vec{f}}{\partial x^{j}} = M^{(j)} \vec{f},$$

$$\left(f_{1}, \partial_{x} f_{1}, \partial_{x}^{2} f_{1}\right) = \tilde{M} \vec{f}.$$
(9)

b) It is easy to see that

$$\vec{c} = \begin{pmatrix} \frac{1}{1-2x+x^2} \\ \frac{-3+3x}{1-2x+x^2} \\ 1 \end{pmatrix}$$
(10)

is a valid and properly normalised solution. You may want to verify that  $\vec{c} \cdot (f_1, \partial_x f_1, \partial_x^2 f_1) = 0$ .

c) Expanding and collecting terms we have with  $a_0 = 1$ 

$$x^r \left( \frac{(r-1)r}{x^2} + \mathcal{O}(x^{-1}) \right) = 0.$$
 (11)

The valid solutions are r = 0 or r = 1. We now expand higher with r = 1

$$(-3+2a_1) + (-2-6a_1+6a_2)x + (-1-5a_1-9a_2+12a_3)x^2 + \mathcal{O}(x^3) = 0$$
(12)

to see that  $a_1 = 3/2$ ,  $a_2 = 11/6$ , and  $a_3 = 25/12$ . We can also explicitly verify that expanding (2) gives these expansions coefficients up to an overall sign.

d) The inverse matrix is

$$\tilde{M}^{-1} = \begin{pmatrix} 1 & 0\\ 2-x & -1+x \end{pmatrix} .$$
(13)

And therefore  $\vec{f} = \tilde{M}^{-1} (f_1, \partial_x f_1)^T$ 

$$f_2 = -1 - \frac{x^2}{2} - \frac{2x^3}{3}.$$
 (14)

**Exercise 2:** Two-mass sunset diagram in  $d = 2 - 2\epsilon$ 

Consider the following integral

$$I_{\alpha\beta\gamma} = - \underbrace{\left[ dk_1 \right] [dk_2]}_{\left[k_1^2 - m_1^2\right]^{\alpha} \left[k_2^2 - m_1^2\right]^{\beta} \left[ (k_1 + k_2 + p)^2 - m_2^2 \right]^{\gamma}}, \quad (15)$$

with  $p^2 = m_2^2 \neq m_1^2$  in  $d = 2 - 2\epsilon$  dimensions. We use the integrals

$$\vec{I} = (m_2^2)^{4-d} \epsilon^2 \left( z^{-4} I_{220}, z^{-2} I_{202}, z^{-4} I_{211}, z^{-1} I_{112} \right)^T$$
(16)

and the variable  $z = m_2/m_1$ .

a) Show that the differential equation matrix is precanonical

$$\partial_{z}\vec{I} = \begin{pmatrix} \frac{4\epsilon}{z} & 0 & 0 & 0\\ 0 & \frac{2\epsilon}{z} & 0 & 0\\ \frac{1}{z(1-z^{2})} & -\frac{1}{z(1-z^{2})} & \frac{z^{2}+(6-4z^{2})\epsilon}{z(1-z^{2})} & -\frac{1+2\epsilon}{z^{2}(1-z^{2})}\\ -\frac{z^{2}}{1-z^{2}} & \frac{1}{1-z^{2}} & -\frac{z^{2}(1+2\epsilon)}{1-z^{2}} & \frac{z^{2}+2\epsilon}{z(1-z^{2})} \end{pmatrix} \vec{I}.$$
 (17)

The boundary conditions can be fixed at z = 1

$$I_{1} = I_{2} = 1 + 2\epsilon + (1 + 2\zeta_{2})\epsilon^{2} + \mathcal{O}(\epsilon^{3}),$$

$$I_{3} = I_{4} = \frac{3}{8}\zeta_{2} + \frac{1}{4} + \left( +\frac{21}{16}\zeta_{3} - \frac{9}{4}\log 2\zeta_{2} + \frac{9}{8}\zeta_{2} - \frac{1}{2}\right)\epsilon + \left( -\frac{63}{16}\zeta_{4} + 9\mathrm{Li}_{4}(\frac{1}{2}) + \frac{9}{2}\log 2^{2}\zeta_{2} + \frac{3}{8}\log 2^{4} + \frac{63}{16}\zeta_{3} - \frac{27}{4}\log 2\zeta_{2} + \frac{1}{2}\zeta_{2} + 1\right)\epsilon^{2} + \mathcal{O}(\epsilon^{3}).$$

$$(18a)$$

$$(18b)$$

We will now try to derive a series expression around z = 1.

- b) Show (18). (for the adventurous)
- c) Consider first the homogenous subsystem for  $\vec{I'} = (I_3, I_4)$  with x = 1 z

$$\partial_x \vec{I'} = \begin{pmatrix} \frac{1-x}{(x-2)x} & -\frac{1}{(x-2)(x-1)^2x} \\ -\frac{(1-x)^2}{(x-2)x} & \frac{1-x}{(x-2)x} \end{pmatrix} \vec{I'} .$$
(19)

Construct  $\tilde{M}$  and  $\bar{M}$ 

$$\bar{M} = \begin{pmatrix} 1 & 0\\ \frac{1-x}{(x-2)x} & -\frac{1}{(x-2)(x-1)^2x}\\ \frac{2(x^2-2x+2)}{(x-2)^2x^2} & \frac{2(3x^2-6x+2)}{(x-2)^2(x-1)^3x^2} \end{pmatrix}$$
(20)

- d) Find a solution  $\vec{c}$  and write down the second-order differential equation for  $I_3$ . Make a Frobenius ansatz. What values of r are allowed?
- e) Build a series solution for r = 0.

f) Construct the first-order differential equation to find the other solution for

$$\vec{c}_2 = \left(\frac{4}{x}\frac{1-x}{2-x}, 1\right).$$
 (21)

- g) Build a series solution for r = -2 and write down the full homogenous solution for the original differential equation.
- h) Now we can consider the inhomogeneity. Show that for the k-th order in  $\epsilon$ , it becomes

$$\vec{\mathcal{I}}^{(k)} = \frac{1}{x(x-2)} \left[ \begin{pmatrix} \frac{1}{1-x} & -\frac{1}{1-x} \\ -(1-x)^2 & 1 \end{pmatrix} \cdot \begin{pmatrix} I_1^{(k)}, I_2^{(k)} \end{pmatrix} + \begin{pmatrix} \frac{4x^2 - 8x - 2}{x-1} & -\frac{2}{(x-1)^2} \\ -2(x-1)^2 & -\frac{2}{x-1} \end{pmatrix} \cdot \begin{pmatrix} I_3^{(k-1)}, I_4^{(k-1)} \end{pmatrix} \right].$$
(22)

i) Now construct a solution up to  $\mathcal{O}(\epsilon^2)$ . Evaluate the result at z = 0.5.

SOLUTION: A Mathematica calculation of this problem is given on the website.

a) It is trivial to derive a differential equation for eg.  $m_2^2$  using reduze. From there we write

$$T = (m_2^2)^{d-4} \epsilon^{-2} \operatorname{diag}\left(\frac{m_2^4}{m_1^4}, \frac{m_2^2}{m_1^2}, \frac{m_2^4}{m_1^4}, \frac{m_2}{m_1}\right)$$
(23)

and hence  $A_z$ .

b) It is clear that  $I_1 = I_2$  and  $I_3 = I_4$  from symmetry for z = 1.  $I_1$  is just a tadpole and trivially just

$$I_1 = I_2 \Big|_{z=1} = (1+\epsilon)^2 \Gamma[1-\epsilon]^2 \Gamma[1+\epsilon]^2 \,.$$
(24)

For  $I_3$  we calculate the graph polynomials

$$\mathcal{U} = x_1 x_2 + x_3 x_2 + x_1 x_3 \,, \tag{25}$$

$$\mathcal{F} = -(x_1 + x_2)\mathcal{U} - (x_1 + x_2)x_3^2.$$
(26)

Therefore the integral is

$$I_3 = (-1)^{2\epsilon} \Gamma(1-\epsilon)^2 \Gamma(2+2\epsilon) \int \mathrm{d}\vec{x} \, x_1 \frac{\mathcal{U}^{1+3\epsilon}}{\mathcal{F}^{2+2\epsilon}} \tag{27}$$

$$= \Gamma(1-\epsilon)^2 \Gamma(2+2\epsilon) \int d\vec{x} \, x_1 \mathcal{U}^{1+3\epsilon} (x_1+x_2)^{-2-2\epsilon} (\mathcal{U}+x_3^2)^{-2-2\epsilon} \,.$$
(28)

Using the Mellin-Barnes theorem to split  $\mathcal{U} + x_3^2$ 

$$I_3 = \Gamma(1-\epsilon)^2 \int_{-i\infty}^{+i\infty} \mathrm{d}\sigma \int \mathrm{d}\vec{x} \Gamma(-\sigma) \Gamma(2+\sigma+2\epsilon) \ x_1 x_3^{2\sigma} (x_1+x_2)^{-2-2\epsilon} \mathcal{U}^{-1-\sigma+\epsilon} \,. \tag{29}$$

We can now solve the  $x_3$  and  $x_2$  integrals

$$I_{3} = \Gamma(1-\epsilon)^{2} \int_{-i\infty}^{+i\infty} \mathrm{d}\sigma \frac{\Gamma(-\sigma)\Gamma(2\sigma+1)\Gamma(-\epsilon-\sigma)\Gamma(\epsilon+\sigma+1)\Gamma(\epsilon+\sigma+2)\Gamma(2\epsilon+\sigma+2)}{\Gamma(-\epsilon+\sigma+1)\Gamma(2\epsilon+2\sigma+3)} \,.$$
(30)

This integral can be solved in terms of  ${}_{3}F_{2}$  functions by considering the residues at  $\sigma = n$ and  $\sigma = n - \epsilon$ . Alternatively, we can solve it numerically for  $\sigma = 1/3 + ix$ 

$$\begin{split} I_3 = &+ \ 0.8668502750680849136771556874922594459571062129525494141508343360137528 \\ &+ \ 0.3628423366548035363008187167277704240129460044840854565583099812335021\epsilon \\ &+ \ 2.897979437584699485862761102760735004697735930030264157054679832034451\epsilon^2 \\ &+ \ \mathcal{O}(\epsilon^3) \,. \end{split}$$

(31)

We have evaluated the integral to 70 digits which is required to perform the rational number fit.

- c) It is trivial to find the homogenous matrix M as given in (19). From there, constructing  $\overline{M}$  is just a matter of calculating derivitives.
- d) We find p = 2

$$\vec{c} = \left(\frac{2}{x-2} - \frac{2}{x}, \frac{2}{x-2} + \frac{2}{x-1} + \frac{2}{x}, 1\right).$$
(32)

Making the ansatz and expanding to the first order, we find r(1 + r) = 0. We hence choose r = 0.

- e) It is easy to see that  $a_i = 1$  for all *i* and hence  $f_1 = 1/(1-x)$  is a solution.
- f) We have

$$(c_2)_j = \sum_{n=0}^{p-1-j} {\binom{p-n}{1+j}} c_{p-n+1} \frac{\partial^{p-n-j-1} f_1}{\partial x^{p-n-j-1}} = \left( \frac{6x^2 - 12x + 4}{(1-x)x(x^2 - 3x + 2)} + \frac{2}{(1-x)^2}, \frac{1}{1-x} \right),$$
(33)

which is equivalent to the given  $\vec{c}_2$ .

g) The solution for  $\vec{c}_2$  is slightly more complicated but can still be written in closed form

$$f_1' = \frac{1}{x^2} + \frac{1}{x} + \frac{3}{4} + \frac{x}{2} + \frac{5x^2}{16} + \frac{3x^3}{16} + \frac{7x^4}{64} + \frac{x^5}{16} + \frac{9x^6}{256} + \frac{5x^7}{256} + \frac{11x^8}{1024} + \frac{3x^9}{512} + \mathcal{O}(x^{10})$$
$$= \sum_{i=0}^{\infty} \frac{i+1}{2^i} x^{i-2} = \frac{4}{x^2(x-2)^2}$$
(34)

The integrated  $f'_1$  can also be found easily

$$f_{1} = f_{0} \int dx f_{1}' = f_{0} \int dx = \frac{1}{1-x} \left( -\frac{1}{x} + \log x + \sum_{i=1}^{\infty} \frac{2+i}{2i} \frac{x^{i}}{2^{i}} \right)$$
$$= -\frac{1}{x} + \log x - 1 + x \left( \log x - \frac{1}{4} \right) + x^{2} \log x + x^{3} \left( \log(x) + \frac{5}{48} \right) + x^{4} \left( \log x + \frac{29}{192} \right) + \dots$$
(35)

The solution matrix F can be found as

$$F = \begin{pmatrix} 1 + x + x^2 + x^3 & -\frac{1}{x} + \log(x) - 1 + x(\log x - \frac{1}{4}) + x^2 \log x + x^3(\log x + \frac{5}{48}) \\ 1 + O(x^4) & \frac{1}{x} + \log(x) - 1 + \frac{x}{4} - \frac{x^3}{48} \end{pmatrix} + \mathcal{O}(x^4).$$
(36)

- h) There are two contributions to  $\mathcal{I}$ 
  - the lower sector contributions from  $I_1$  and  $I_2$  that are governed by the slices of  $(A_x)_{3..4,1..2}$ . These can be read of from the  $\epsilon^0$  part of (17) after substituting  $z \to 1-x$ .
  - the lower order contribution from  $I_3$  and  $I_4$  that are governed by the  $\mathcal{O}(\epsilon)$  part of  $(A_x)_{3.4,3.4}$ .
- i) We calculate

$$G^{(k)} = F \cdot \left( \int \mathrm{d}x F^{-1} \frac{1}{2} \left( \vec{\mathcal{I}}^{(k)}, \vec{\mathcal{I}}^{(k)} \right) + \mathrm{diag}(c_1^{(k)}, c_2^{(k)}) \right)$$
(37)

order-by-order and then obtain  $I_3 = G_{11} + G_{12}$  and  $I_4 = G_{21} + G_{22}$ . We can then take the limit  $x \to 0$  to match the integration constants. Since we have a series expansion, this is fairly trivial. For k = 0,

$$G^{(0)} = \begin{pmatrix} c_1^{(0)} & -\frac{c_2^{(0)}}{x} + c_2^{(0)}(\log x - 1) \\ c_1^{(0)} & \frac{c_2^{(0)}}{x} + c_2^{(0)}(\log x - 1) \end{pmatrix} + \mathcal{O}(x) \,.$$
(38)

Since the limit  $x \to 0$  is finite,  $c_2^{(0)} = 0$ . Matching (18), we then find  $c_1^{(0)} = \frac{1}{4} + \frac{\pi^2}{16}$ . Pluggin in numbers we find

$$\vec{I} = \begin{pmatrix} 1\\1\\1.3581\\0.4669 \end{pmatrix} + \begin{pmatrix} -0.7725\\0.6137\\0.4189\\0.3800 \end{pmatrix} \epsilon + \begin{pmatrix} 2.5883\\2.4781\\3.3107\\1.1768 \end{pmatrix} \epsilon^2 + \begin{pmatrix} -1.1793\\2.1104\\1.9080\\1.2225 \end{pmatrix} \epsilon^3 + \mathcal{O}(\epsilon^4)$$
(39)