

Practical guide to loop integration

Summer Term 2024 Dr Y. Ulrich

23 April 2024

Issued:

Exercise Sheet 2

https://yannickulrich.com/loop-integration

Exercise 1: Sunset diagram Consider the following integral

$$I(a_1, a_2, a_3; \mathcal{N}) = \mathcal{N} \times \underbrace{ \begin{cases} a_1 \\ a_3 \end{cases}}_{a_2} = \int [dk_1][dk_2] \frac{\mathcal{N}}{\left[k_1^2\right]^{a_1} \left[k_2^2\right]^{a_2} \left[(k_1 - k_2 - p)^2 - m^2\right]^{a_3}}$$
(1)

with $p^2 = m^2 \neq 0$ and an arbitrary numerator \mathcal{N} .

- a) Find a complete family. We know that it will need $\ell(1+\ell+2\rho)/2=5$ propagators.
- b) Identify the sectors in which all integrals vanish.
- c) Consider the IBP generated through $\partial_{k_1^{\mu}}(k_1^{\mu}I)$. Use it to show that

$$\int [\mathrm{d}k_1][\mathrm{d}k_2] \frac{k_2 \cdot p}{\left[k_1^2\right] \left[k_2^2\right] \left[(k_1 - k_2 - p)^2 - m^2\right]^2} = \frac{3 - d}{2} \int [\mathrm{d}k_1][\mathrm{d}k_2] \frac{1}{\left[k_1^2\right] \left[k_2^2\right] \left[(k_1 - k_2 - p)^2 - m^2\right]}$$
(2)

- d) Now find all six seed identities as a function of a_1, \ldots, a_5 .
- e) Implement Laporta's algorithm to solve the system up to r=4 and s=1 for sector 7 and its subsectors.

SOLUTION:

a) We choose to complete the family as follow

$$I(a_1, a_2, a_3, a_4, a_5) = \int [dk_1][dk_2] \frac{1}{\left[k_1^2\right]^{a_1} \left[k_2^2\right]^{a_2} \left[(k_1 - k_2 - p)^2 - m^2\right]^{a_3} \left[k_1 \cdot p\right]^{a_4} \left[k_2 \cdot p\right]^{a_5}}.$$

Note that this is not a unique solution

b) The sectors 1-6 are zero

$$I(a_1, 0, 0, 0, 0) = \int [dk_1][dk_2] \frac{1}{[k_1^2]^{a_1}},$$

$$I(0, a_2, 0, 0, 0) = \int [dk_1][dk_2] \frac{1}{[k_2^2]^{a_2}},$$

$$I(a_1, a_2, 0, 0, 0) = \int [dk_1][dk_2] \frac{1}{[k_1^2]^{a_1}[k_2^2]^{a_2}},$$

$$I(0, 0, a_3, 0, 0) = \int [dk_1][dk_2] \frac{1}{[(k_1 - k_2 - p)^2 - m^2]^{a_3}},$$

$$I(a_1, 0, a_3, 0, 0) = \int [dk_1][dk_2] \frac{1}{[k_1^2]^{a_1}[(k_1 - k_2 - p)^2 - m^2]^{a_3}}.$$

c) From

$$0 = \int [\mathrm{d}k_1][\mathrm{d}k_2] \partial_{k_1^{\mu}} \left(k_1^{\mu} \frac{1}{\left[k_1^2\right]^{a_1} \left[k_2^2\right]^{a_2} \left[(k_1 - k_2 - p)^2 - m^2\right]^{a_3} \left[k_1 \cdot p\right]^{a_4} \left[k_2 \cdot p\right]^{a_5}} \right)$$

we find

$$0 = (d - 2a_1 - a_3 - a_4) - a_3 \mathbf{1}^{-3} + a_3 \mathbf{2}^{-3} + 2a_3 \mathbf{5}^{-3}.$$

with $a_1 = a_2 = a_3 = 1$ and $a_4 = a_5 = 0$, we find our relation

$$\begin{split} 0 &= (d-3)I(1,1,1,0,0) - I(0,1,2,0,0) + I(1,0,2,0,0) + 2I(1,1,2,0,-1) \\ \Rightarrow I(1,1,2,0,-1) &= \frac{3-d}{2}I(1,1,1,0,0) \,. \end{split}$$

d) We find

$$0 = -2a_1 - a_3 - a_4 + d - a_3 \mathbf{1}^{-3} \mathbf{3}^{+} + a_3 \mathbf{2}^{-3} \mathbf{3}^{+} + 2a_3 \mathbf{5}^{-3} \mathbf{3}^{+}$$

$$0 = -a_1 + a_3 - a_1 \mathbf{2}^{-1} \mathbf{1}^{+} + a_1 \mathbf{3}^{-1} \mathbf{1}^{+} + 2a_1 \mathbf{4}^{-1} \mathbf{1}^{+} - 2a_1 \mathbf{5}^{-1} \mathbf{1}^{+} - a_3 \mathbf{1}^{-3} \mathbf{1}^{+}$$

$$+ a_3 \mathbf{2}^{-3} \mathbf{3}^{+} + 2a_3 \mathbf{4}^{-3} \mathbf{3}^{+} - a_4 \mathbf{5}^{-4} \mathbf{4}^{+}$$

$$0 = -2a_1 \mathbf{4}^{-1} \mathbf{1}^{+} - 2a_3 \mathbf{4}^{-3} \mathbf{1}^{+} + 2a_3 \mathbf{5}^{-3} \mathbf{1}^{+} + 2a_3 m^2 \mathbf{3}^{+} - a_4 m^2 \mathbf{4}^{+}$$

$$0 = -a_2 + a_3 - a_2 \mathbf{1}^{-2} \mathbf{1}^{+} + a_2 \mathbf{3}^{-2} \mathbf{1}^{+} + 2a_2 \mathbf{4}^{-2} \mathbf{1}^{+} - 2a_2 \mathbf{5}^{-2} \mathbf{1}^{+} + a_3 \mathbf{1}^{-3} \mathbf{1}^{+}$$

$$- a_3 \mathbf{2}^{-3} \mathbf{1}^{+} - 2a_3 \mathbf{5}^{-3} \mathbf{1}^{+} - a_5 \mathbf{4}^{-5} \mathbf{1}^{+}$$

$$0 = -2a_2 - a_3 - a_5 + d + a_3 \mathbf{1}^{-3} \mathbf{1}^{+} - a_3 \mathbf{2}^{-3} \mathbf{1}^{+} - 2a_3 \mathbf{4}^{-3} \mathbf{1}^{+}$$

$$0 = -2a_2 \mathbf{5}^{-2} \mathbf{1}^{+} + 2a_3 \mathbf{4}^{-3} \mathbf{1}^{+} - 2a_3 \mathbf{5}^{-3} \mathbf{1}^{+} - 2a_3 m^2 \mathbf{3}^{+} - a_5 m^2 \mathbf{5}^{+}$$

e) The implementation can be found online:

https://gitlab.com/yannickulrich/loop-integration/-/blob/root/code/sheet2.m

Exercise 2: Sunset diagram using computer codes

Consider again the same integral (1) but now with $p^2 = s \neq m^2$. Perform the reduction using reduze or kira for all integrals with $r \leq 4$ and $s \leq 1$.

- a) Make a list of all 75 integrals you want to calculate using a computer program.
- b) Perform the reduction of all integrals without specifying a basis of master integrals. How many master integrals do you find?
- c) Consider the following possible choices of master integrals. Which ones do you prefer and why?

$$\vec{I}_{1} = \begin{pmatrix} I(1,1,1;1) \\ I(1,1,2;1) \end{pmatrix}, \qquad \vec{I}_{2} = \begin{pmatrix} I(1,1,1;1) \\ I(1,1,1;p \cdot k_{1}) \end{pmatrix}, \qquad \vec{I}_{3} = \begin{pmatrix} I(1,2,1;1) \\ I(1,1,2;1) \end{pmatrix}. \tag{3}$$

SOLUTION:

a) We can use the following Mathematica program

```
RST[sunset[a__]] := {
  (* r *) Total[Select[{a}, # > 0 &]],
  (* s *) -Total[Select[{a}, # < 0 &]],
  (* t *) Length[Select[{a}, # > 0 &]]
IsInRange[\{r_, s_, t_\}] := 0 \le r \le 4 \&\& s \le 1 \&\& t \ge 2
request = Select[
  Flatten@Outer[
    sunset,
    {-1, 0, 1, 2}, (* propagator 1 *)
    {-1, 0, 1, 2}, (* propagator 2 *)
    {-1, 0, 1, 2}, (* propagator 3 *)
    {0, -1}, (* auxilary propagator 1 *)
    \{0, -1\} (* auxilary propagator 1 *)
  ],
  IsInRange@*RS
];
Export["req.txt", request]
```

b) To set up reduze and kira we need to first specify the kinematics as config/kinematics.yaml

```
kinematics:
  incoming_momenta: [p]
  outgoing_momenta: [q]
  momentum_conservation: [q,p]
  kinematic_invariants:
    - [s, 2]
    - [m2, 2]
```

```
scalarproduct_rules:
     - [[p,p], "s"]
and the integral family as config/kinematics.yaml
integralfamilies:
  - name: "sunset"
    loop_momenta: [k1, k2]
    propagators:
      - [ "k1", "0"]
      - [ "k2", "0"]
      - [ "k1-k2-p",
                      "m2"]
      - { bilinear: [["k1","p"], "0"] }
      - { bilinear: [["k2","p"], "0"] }
Next we specify the job we want to execute
jobs:
  - setup_sector_mappings: {}
  - reduce_sectors:
      sector_selection:
        select_recursively:
          - [sunset, 7]
      identities:
        ibp:
          - { r: [t, 5], s: [0, 2] }
  - select_reductions:
      input_file: req.txt
      output_file: tmp/req.txt.tmp
  - reduce_files:
      equation_files: ["tmp/req.txt.tmp"]
      output_file: "tmp/req2.txt.sol"
      # preferred_masters_file: "masters2.m"
    export:
      input_file: tmp/req2.txt.sol
      output_file: req2.sol.m
      output_format: mma
      # preferred_masters_file: "masters2.m"
```

- c) To change the basis we specify preferred_masters_file and rerun the reduction. Comparing the results we find that
 - \vec{I}_1 introduces denominators of the form d-4 meaning that we need to know the masters higher than $\mathcal{O}(\epsilon^0)$
 - \vec{I}_2 complicates the calculation of the masters
 - \vec{I}_3 introduces complicated denominators of the form (3-d)(8-3d) which is not ideal.